

- d. Assume we have the complex numbers A and z , where they can be represented in polar form as $A = a e^{j\theta}$, and $z = b e^{j\beta}$. Assume that their conjugates are represented by A^* and z^* respectively. Show that $Az^n + A^*(z^*)^n$ can be written as:

$$Az^n + A^*(z^*)^n = x[n]\cos(\beta n + \theta)$$

Also show the expression for $x[n]$.

2. (25 pts) Assume a continuous-time system is represented by the following differential equation $\frac{d^2y}{dt^2} + 5\frac{dy}{dt} + 6y(t) = 2\frac{dx}{dt} + x(t)$, answer the following questions:

- a. Find the characteristic roots for the system.
- b. Find the zero-input response for the system. Assume the initial conditions $y(0) = 0$, and $y'(0) = 1$.

c. Is the system asymptotically stable? Justify your answers.

d. Determine the impulse response of the system.

e. Is the system causal? Justify your answer.

2. (20 pts) Assume a discrete-time system is represented by the following difference equation $y[n + 2] + 5y[n + 1] + 6y[n] = 2x[n + 1] + x[n]$, answer the following questions with initial conditions $y[-2] = 0$, $y[-1] = 1$.

a. Find the characteristic roots for the system.

b. Find the zero-input response.

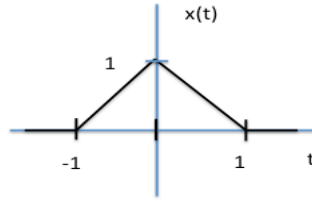
c. Is the system asymptotically stable? Justify your answers.

d. Find the impulse response.

3. (20 pts) (Convolution with continuous-time signals)

a. Determine the zero-state output of a system represented by the impulse response $h(t) = \frac{1}{t+1} u(t)$, and the input to the system is the step function $x(t) = 4u(t)$.

- b. Assume the triangular wave shown below is fed to a system represented by the impulse response $h(t) = \sum_{k=-1}^{k=1} \delta(t - \frac{3}{2}k)$, (k takes integer values), derive and plot the zero-state response.



4. (20 pts) (Convolution with discrete-time signals)
- a. Determine the zero-state output of a system represented by the impulse response $h[n] = (0.2)^n u[n]$, and the input to the system is the function $x[n] = (5)^n u[n]$.

- b. Determine the zero-state output of a system represented by the impulse response $h[n] = n(u[n] - u[n - 4])$ and when the input to the system is $x[n] = (u[n] - u[n - 4])$.